

Robust Motion Estimation for On-Board CBCT Imaging using an Angular Sampling Artifact Model

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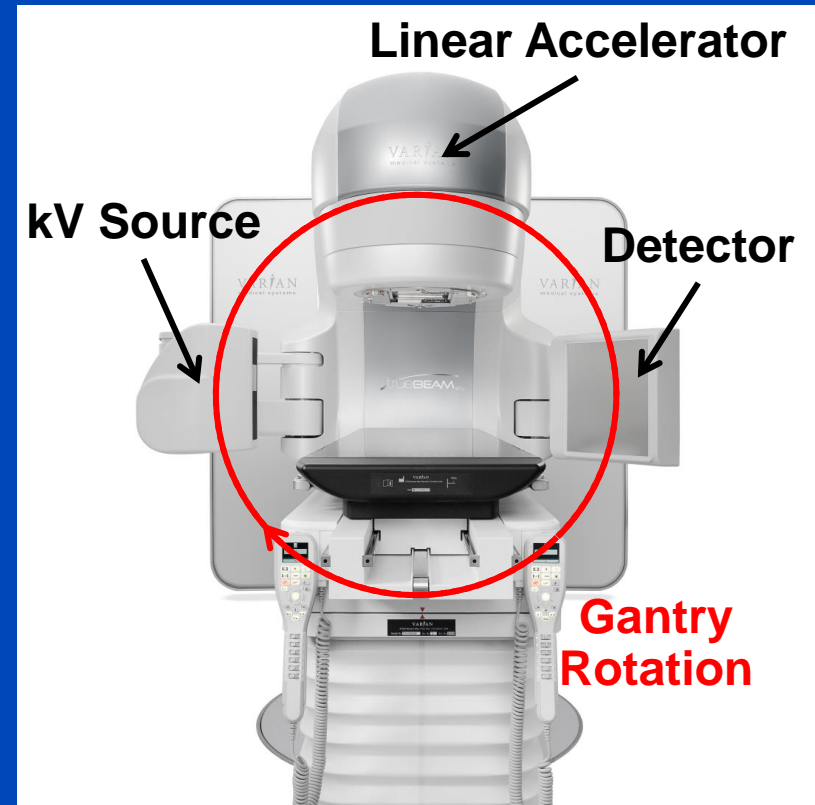
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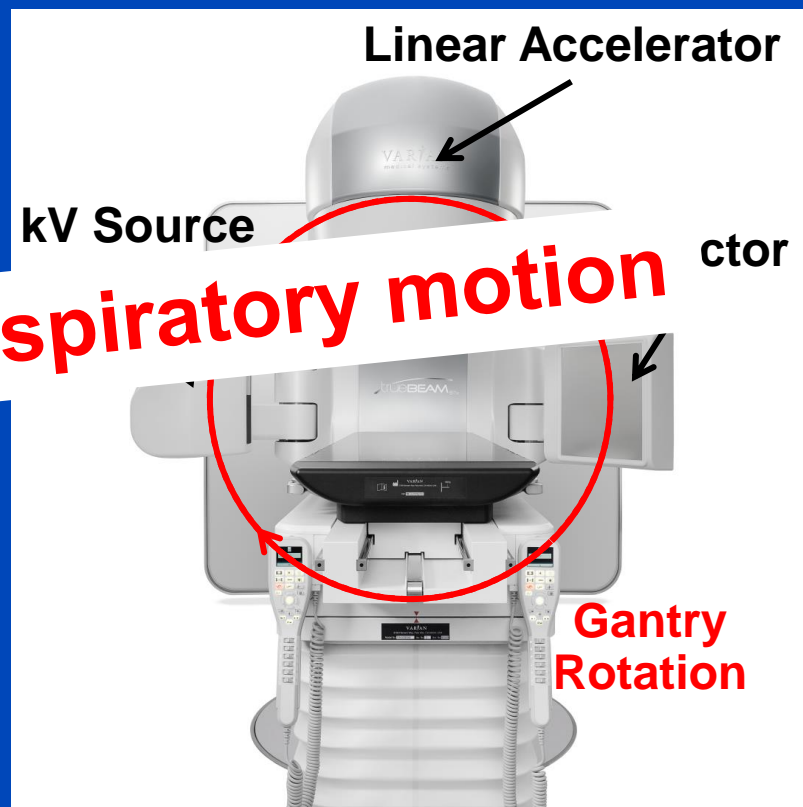
Slowly Rotating CBCT Devices

- Image-guided radiation therapy (IGRT)
 - CBCT imaging unit mounted on gantry of a LINAC treatment system
 - E.g. used for patient positioning
- Maximum gantry rotation speed of 6° per second
 - Much slower than clinical CT devices (60 s and more vs. about 0.28 s per rotation)
- Breathing cycle about 2 to 5 seconds
 - i.e. 12 to 30 respirations per minute (rpm) and thus per scan



Slowly Rotating CBCT Devices

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 - CBCT imaging unit mounted on gantry of a LINAC treatment system
 - E.g. used for patient positioning
- **Task: Account for respiratory motion**
 - Much slower than clinical CT devices (60 s and more vs. about 0.28 s per rotation)
- Breathing cycle about 2 to 5 seconds
 - i.e. 12 to 30 respirations per minute (rpm) and thus per scan



Prior Art in IGRT (Respiratory-Correlated Reconstructions)

- **Respiratory binning and independent reconstruction**
 - Sonke et al., “*Respiratory correlated cone beam CT*,” Med. Phys. 32(4), 1176–1186 (2005).
 - Dietrich et al., “*Linac-integrated 4D cone beam CT: First experimental results*,” Phys. Med. Biol. 51(11), 2939–2952 (2006).
 - Li et al., “*Four-dimensional cone-beam computed tomography using an on-board imager*,” Med. Phys. 33(10), 3825–3833 (2006).
- **Dedicated acquisition techniques**
 - Lu et al., “*Four-dimensional cone beam CT with adaptive gantry rotation and adaptive data sampling*,” Med. Phys. 34(9), 3520–3529 (2007).
 - Li et al., “*Optimizing 4D cone-beam CT acquisition protocol for external beam radiotherapy*,” Int. J. Radiat. Oncol., Biol., Phys. 67(4), 1211–1219 (2007).
- **Not each region is affected by motion**
 - Leng et al., “*Streaking artifacts reduction in four-dimensional cone-beam computed tomography*,” Med. Phys. 35(10), 4649–4659 (2008).
 - Bergner et al., “*Autoadaptive phase-correlated (AAPC) reconstruction for 4D CBCT*,” Med. Phys. 36(12), 5695–5706 (2009).
 - Ahmad et al., “*Four-dimensional volume-of-interest reconstruction for cone-beam computed tomography-guided radiation therapy*,” Med. Phys. 38(9), 5646–5656 (2011).
- **Motion-compensated reconstruction**
 - Li et al., “*Motion correction for improved target localization with on-board cone-beam CT*,” Phys. Med. Biol. 51(2), 253–267 (2006).
 - Rit et al., “*On-the-fly motion-compensated cone-beam CT using an a priori model of the respiratory motion*,” Med. Phys. 36(6), 2283–2296 (2009).
 - Li et al., “*Enhanced 4D cone-beam CT with inter-phase motion model*,” Med. Phys. 51(9), 3688–3695 (2007).

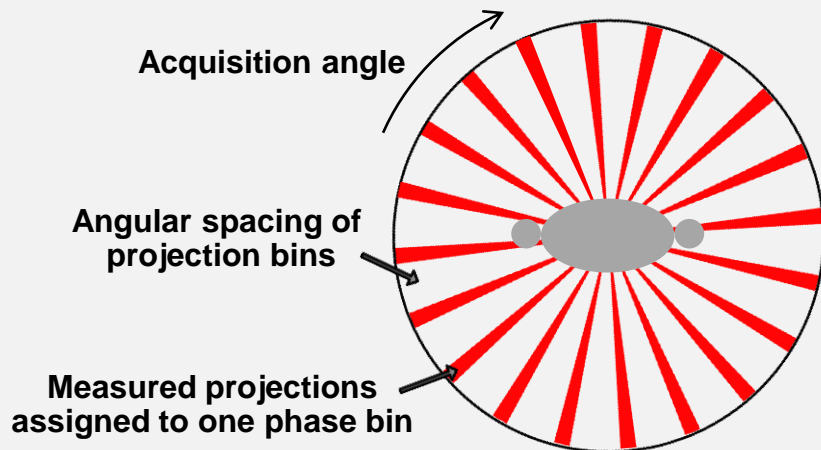
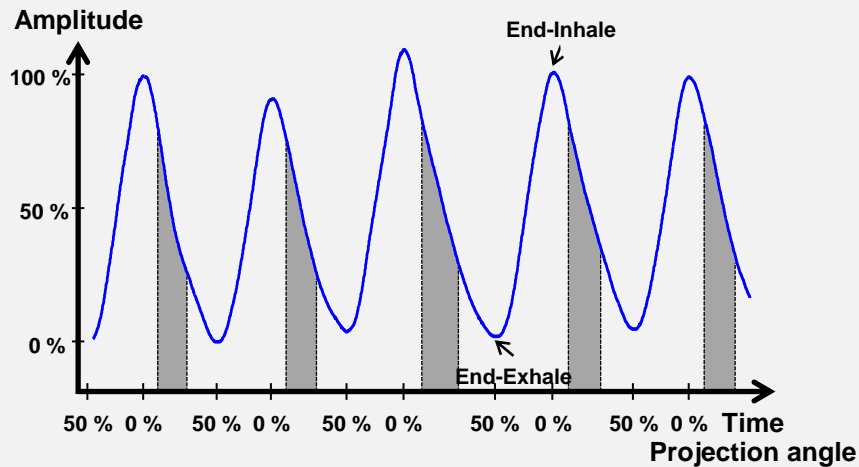
Prior Art in IGRT (Respiratory-Correlated Reconstructions)

- Respiratory binning and independent reconstruction
Angular sampling artifacts
- Dedicated acquisition techniques
Increased acquisition time
- Not each region is affected by motion
Remaining artifacts in volume-of-interest
- Motion-compensated reconstruction
**Increased patient dose or
do not account for inter-fractional variations**

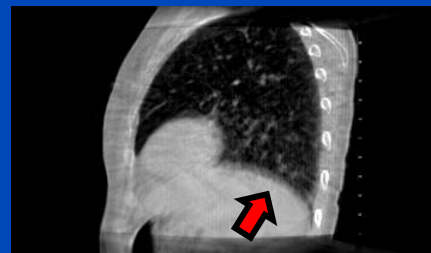
Aim

- **Provide high quality respiratory-correlated 4D volumes from on-board CBCT scans**
 - Image quality comparable to that of motionless regions (e.g. head, neck, ...)
- **Do this with a standard acquisition protocol**
 - Without any particularly slow, multiple or adaptive gantry rotation technique
 - These are not accepted in clinical routine, e.g. due to long acquisition times
- **Do this without other prior information of higher temporal sampling such as a 4D planning CT**
 - Account for inter-fractional variations in breathing motion

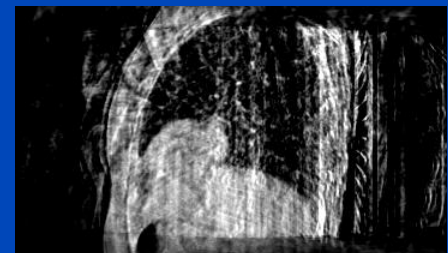
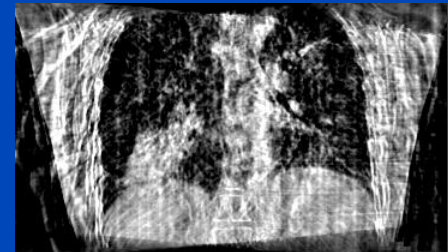
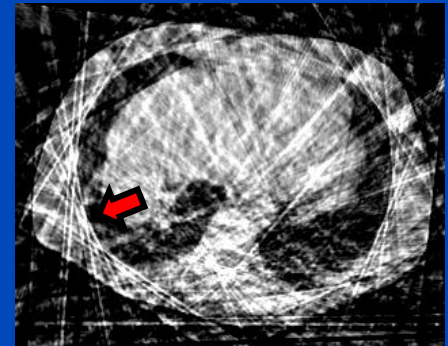
Retrospective Gating



Without gating (3D):
Motion artifacts



With gating (4D):
Sparse-view artifacts

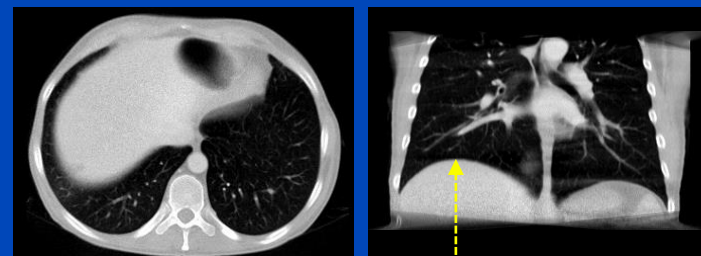


Motion Compensation (MoCo)

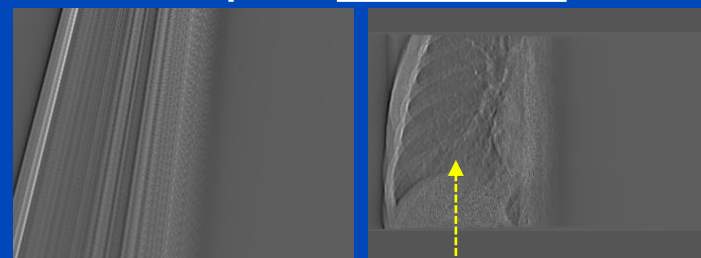
- Use all projection data for each phase to be reconstructed
 - Even those of other phase bins
 - Compensate for motion using motion vector fields (MVF)
 - In our case MVFs are estimated from phase-correlated (gated) reconstructions
- Backproject-then-warp
 - Backproject sparse data along straight lines, warp with respect to the MVFs, and superimpose warped backprojections of all sparse data
 - Projection data p , phase-correlated reconstruction operator X_{PCF}^{-1} , MVF T_j^i from phase bin j to phase bin i

$$f_{\text{MoCo}(i)} := \sum_j \left(X_{\text{PCF}(j)}^{-1} p \right) \circ T_j^i$$

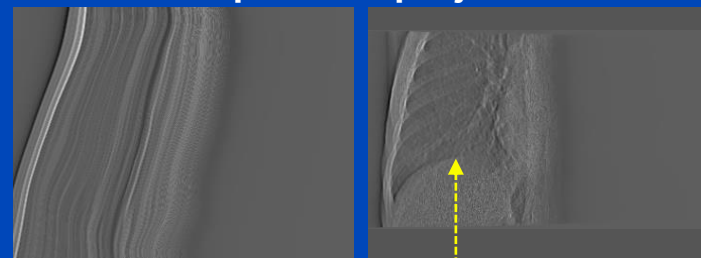
Ground truth in end-exhale



Backprojection on (straight) acquisition lines of a projection acquired in end-inhale

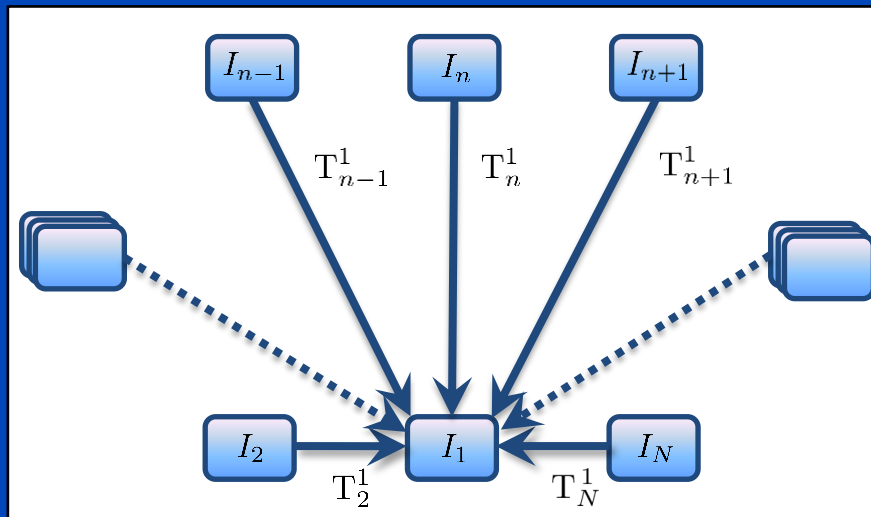


Warped backprojection



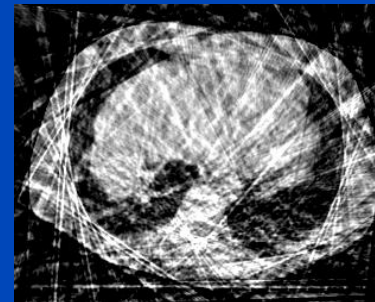
A Standard Motion Estimation and Compensation Approach (sMoCo)

- Motion estimation via standard 3D-3D registration

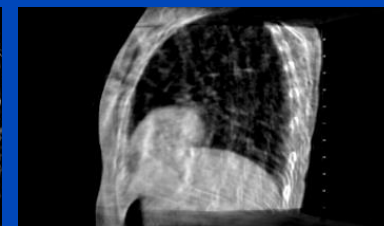
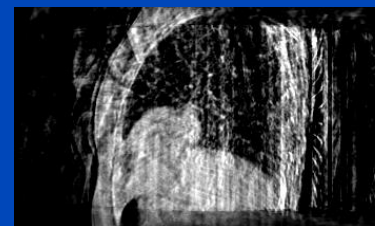
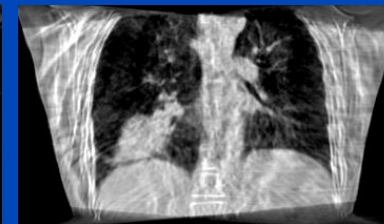
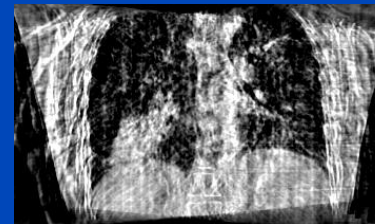
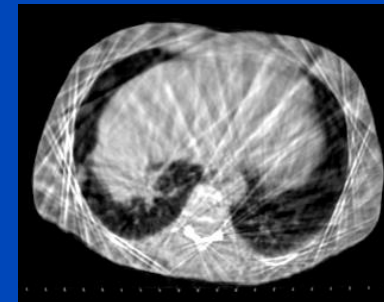


- Has to be repeated for each reconstructed phase
- Streak artifacts from gated reconstructions propagate into sMoCo results

Gated 4D CBCT

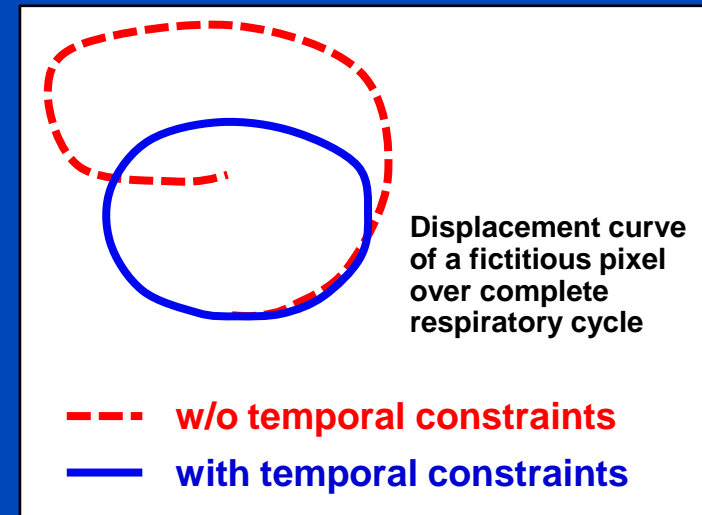
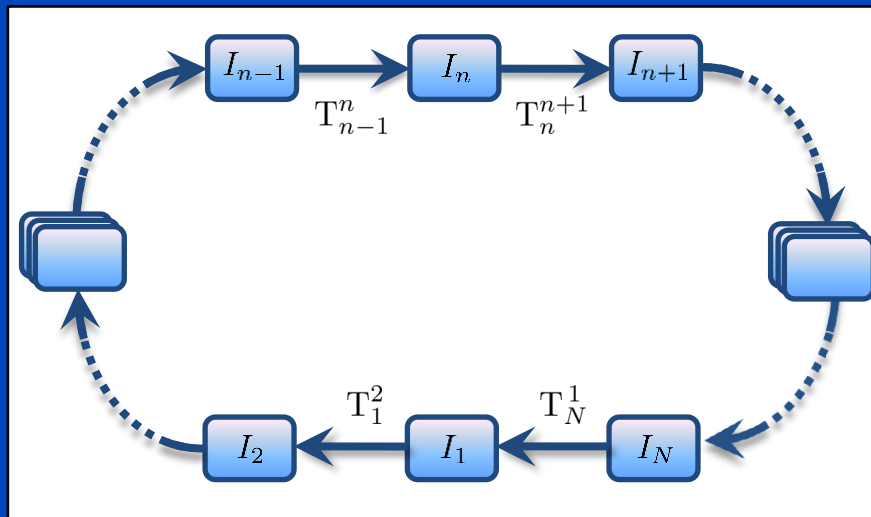


sMoCo



A Cyclic Motion Estimation and Compensation Approach

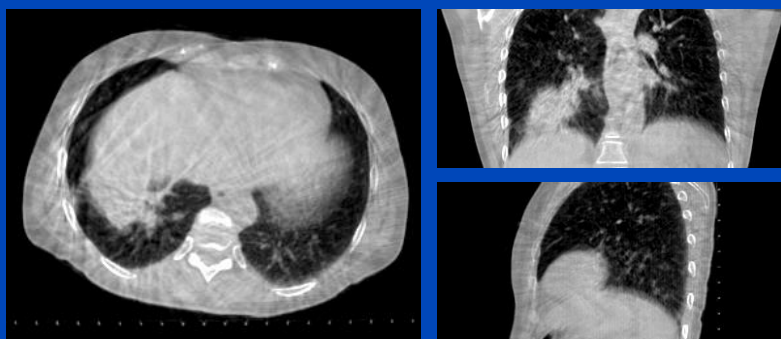
- Motion estimation only between adjacent phases
 - All other MVFs given by concatenation



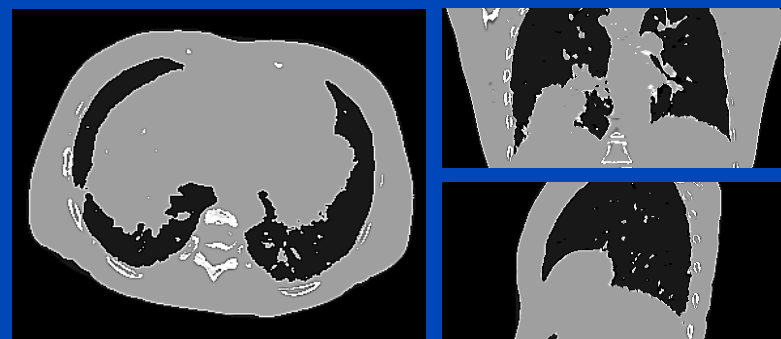
- Incorporate additional knowledge
 - A priori knowledge of quasi periodic breathing pattern
 - Non-cyclic motion is penalized
 - Error propagation due to concatenation is reduced

Angular Sampling Artifact Model

- Create second series of images with sparse-view artifacts but without breathing motion
- Eliminate breathing motion information
 - Threshold-based segmentation of 3D CBCT
- Simulate measurement and reconstruction process
 - Forward projection of segmented image
 - Backprojection at same angles as for gated 4D CBCT



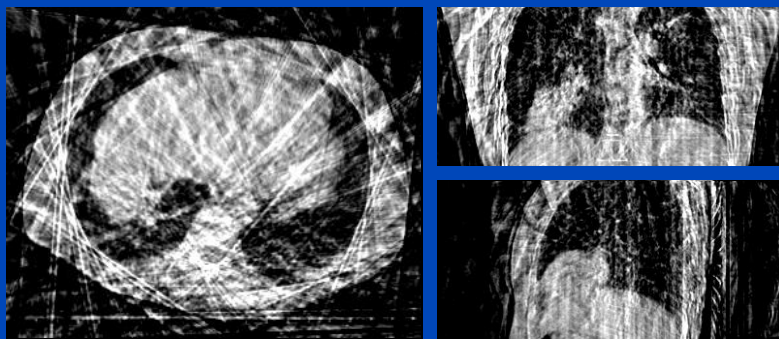
3D CBCT



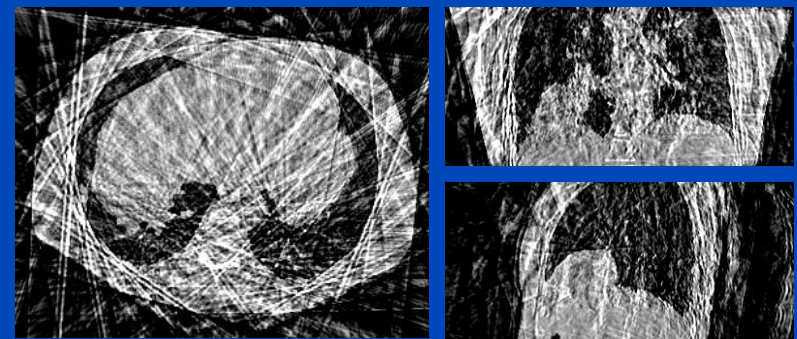
Segmented Image

Angular Sampling Artifact Model

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- Eliminate breathing motion information
 - Threshold-based segmentation of 3D CBCT
- Simulate measurement and reconstruction process
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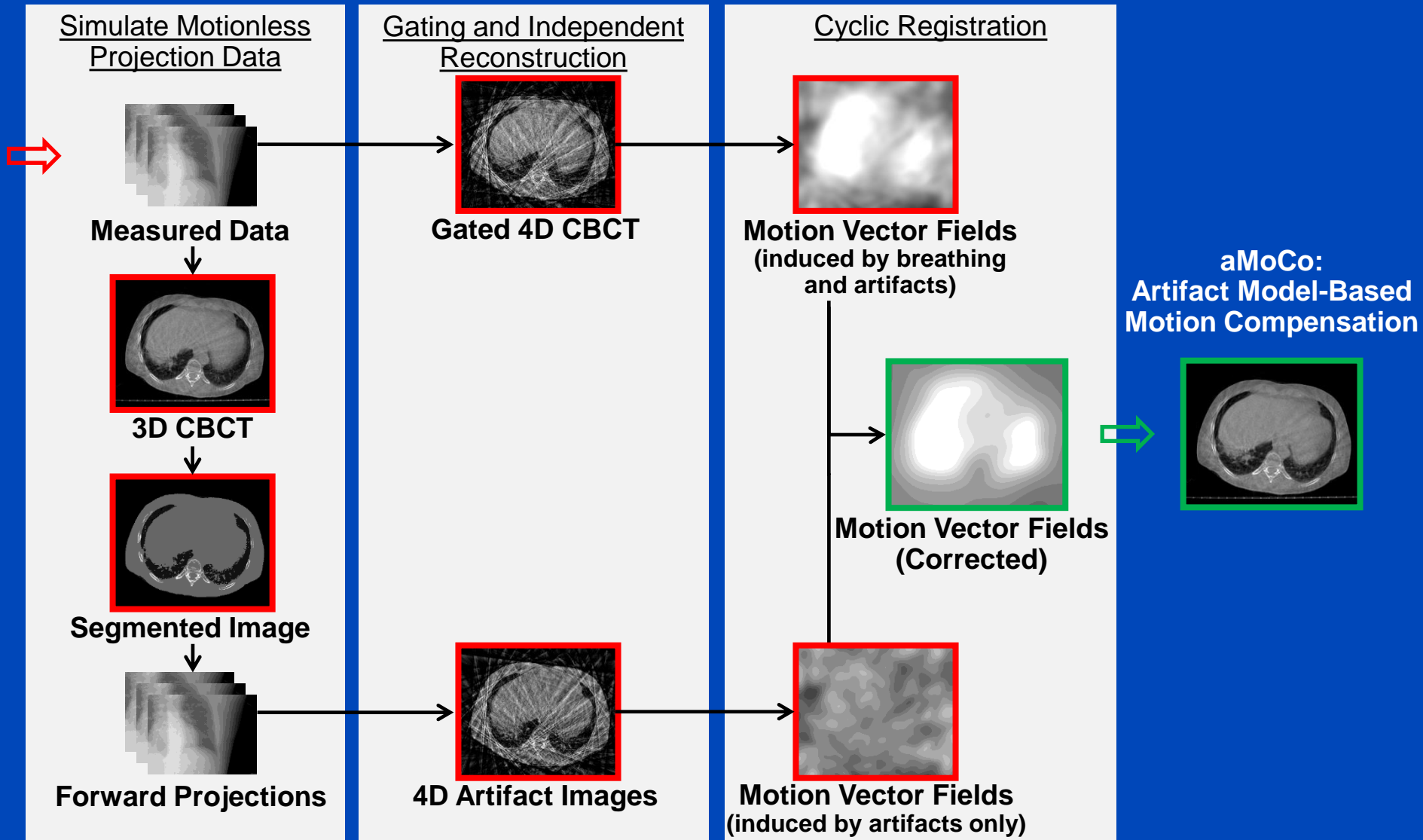


Gated 4D CBCT



4D Artifact Images

Motion Estimation using an Angular Sampling Artifact Model



Simulation and Measurements

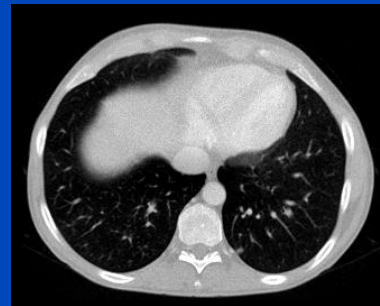
- **Acquisition data:**

- Varian OBI geometry
 - » RF = 1000 mm,
 - » RD = 500 mm,
 - » 1024 × 768 Pixel (0.388² mm²)
- Half Fan – Full Scan
- Number of projections: ~650
- Time for 360° rotation: $T_{\text{rot}} = 60 \text{ s}$

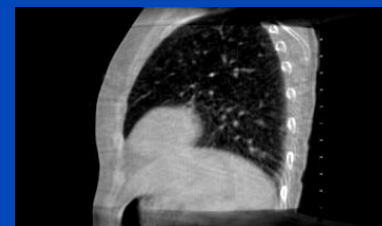
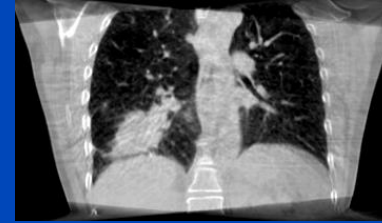
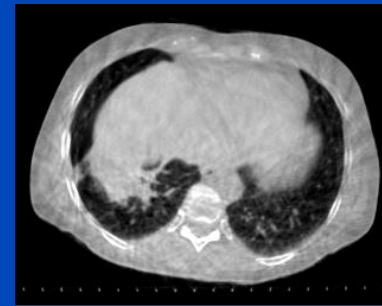
- **Reconstruction data:**

- Volume size: 512 × 512 × 210
- Voxel spacing: 1 × 1 × 1 mm³
- Number phases: N = 20
- Phase bin width: 10%

Ground Truth of
Simulation (15 rpm)



Patient Dataset
(26 rpm)



Simulated Data – Results

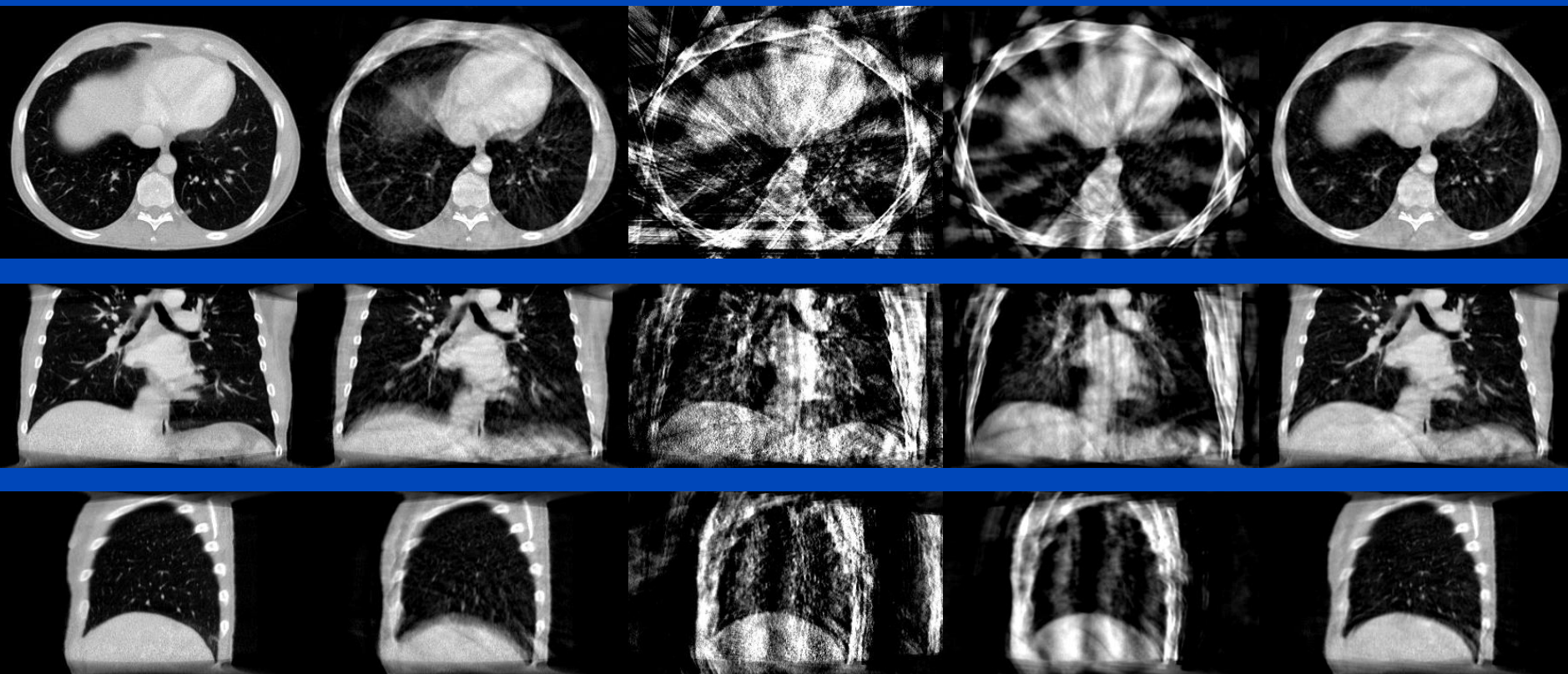
GT
Ground Truth

3D CBCT
Standard

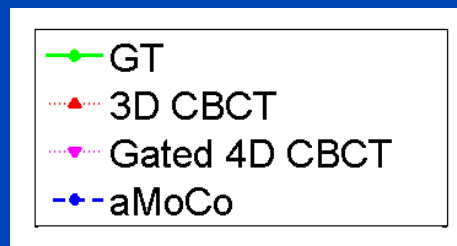
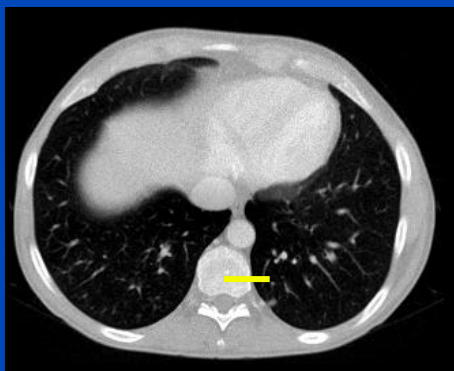
Gated 4D CBCT
Conventional
Phase-Correlated

sMoCo
Standard Motion
Compensation

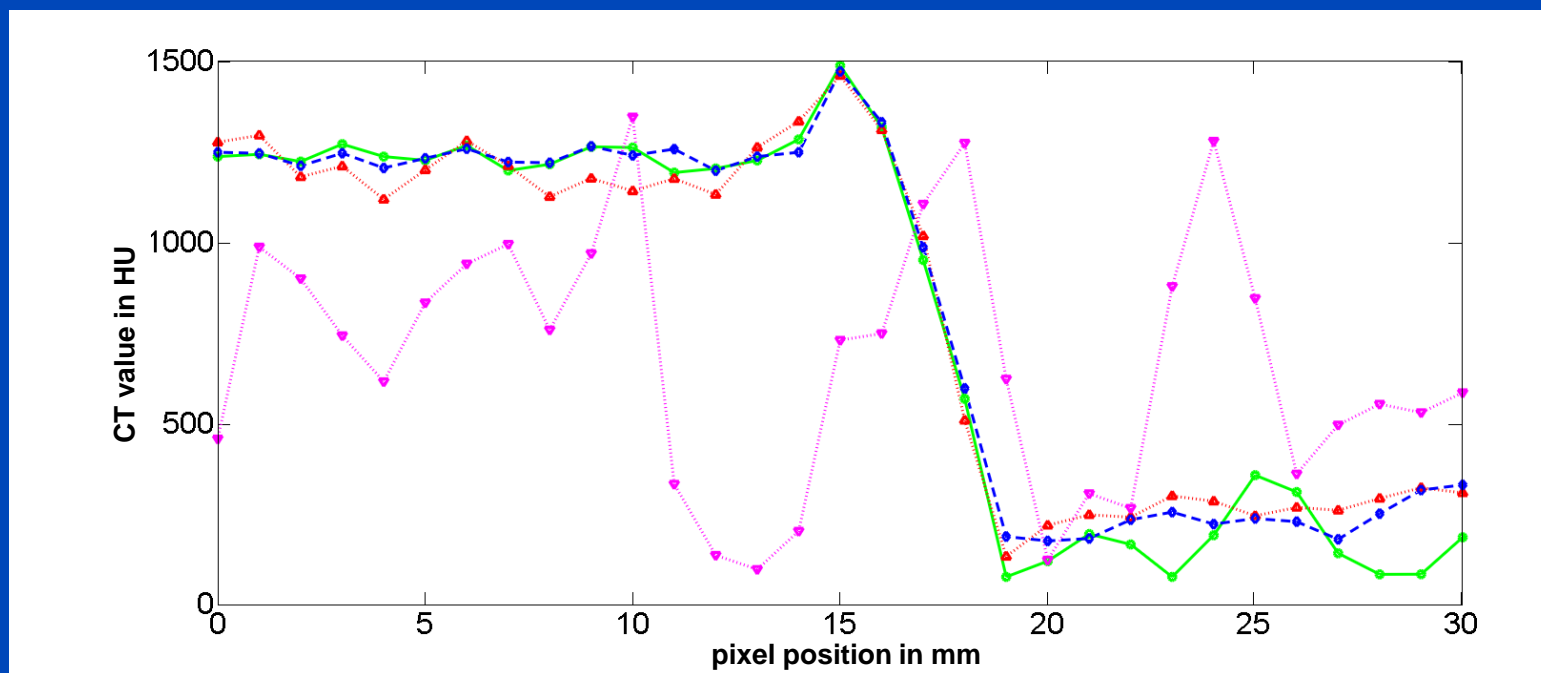
aMoCo
Artifact Model-Based
Motion Compensation



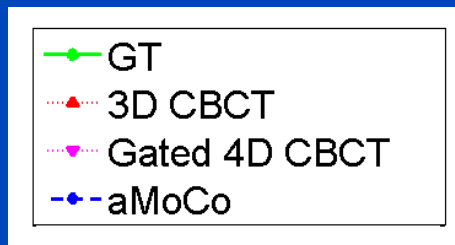
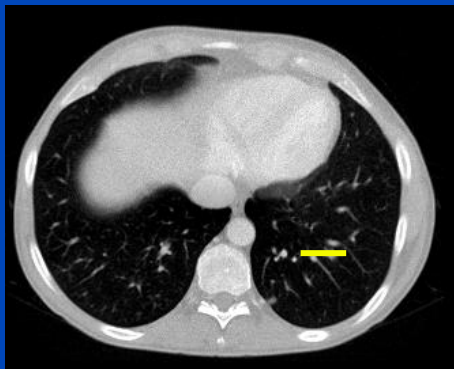
Simulated Data – Edge Profiles



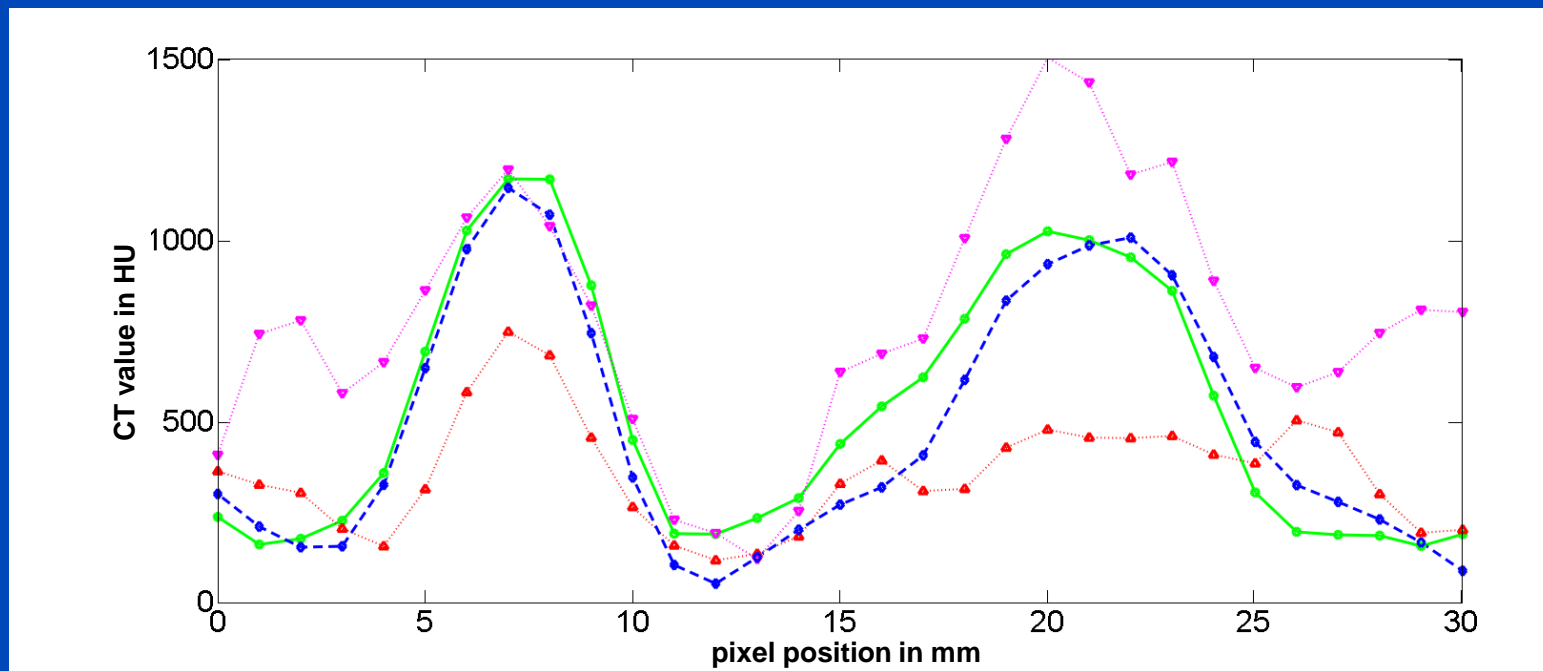
Motionless edge (vertebral body)



Simulated Data – Edge Profiles



Pulmonary blood vessels



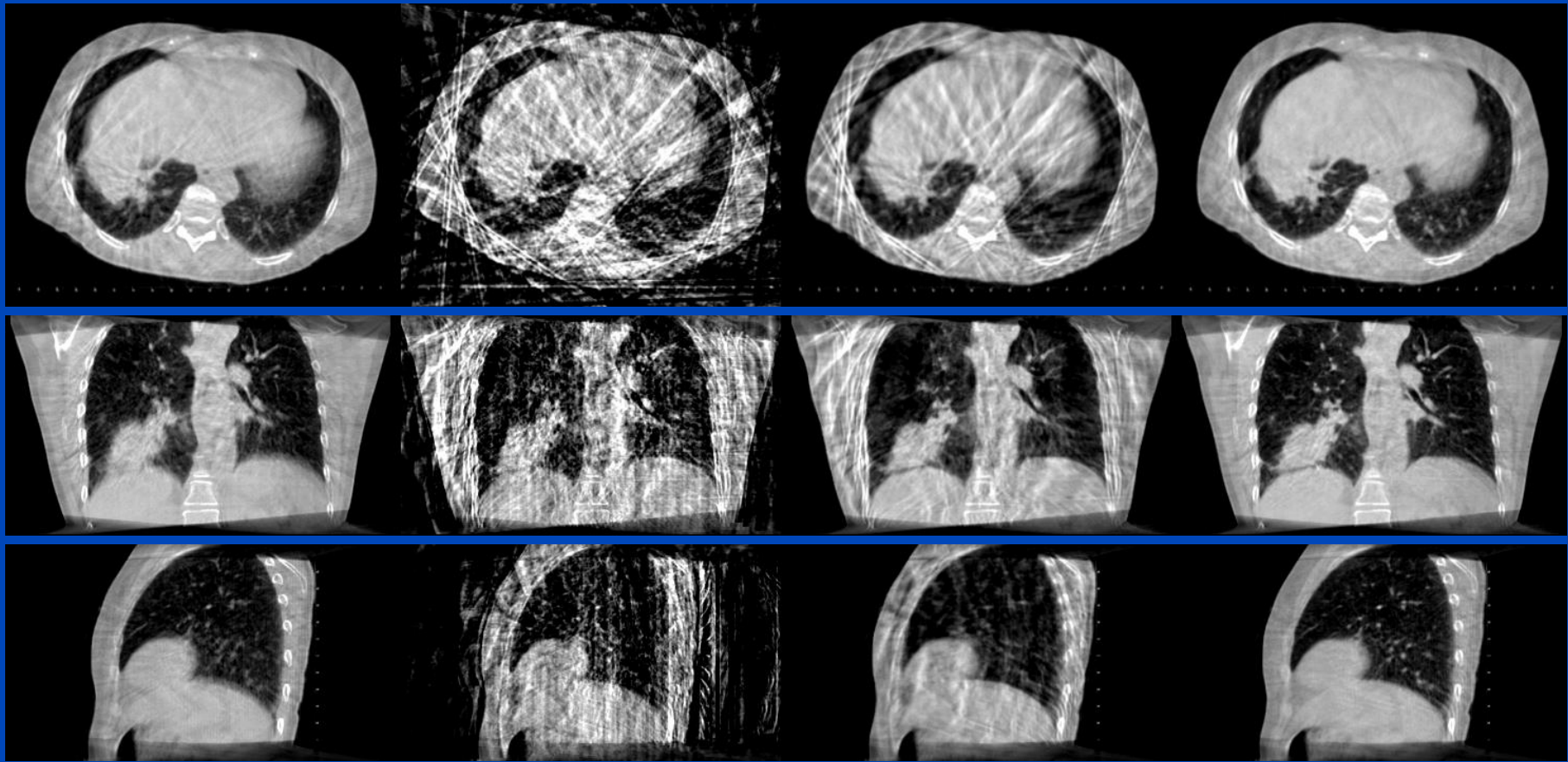
Patient Data – Results

3D CBCT
Standard

Gated 4D CBCT
Conventional
Phase-Correlated

sMoCo
Standard Motion
Compensation

aMoCo
Artifact Model-Based
Motion Compensation



Summary

- **Severe sparse-view artifacts**
 - deteriorate image quality of conventional phase-correlated images (gated 4D CBCT) from slowly rotating devices,
 - negatively affect motion estimation on these images.
- **Motion estimation**
 - based on standard deformable 3D-3D registration is highly sensitive to these artifacts and in addition heavily time consuming,
 - based on cyclic registration has a reduced amount of computations,
 - » In addition, this allows to incorporate temporal constraints to reduce error propagation and to reduce artifact sensitivity
 - using an correction based on an artifact model shows a highly decreased sensitivity to sparse-view artifacts.
- **Motion-compensated image reconstruction**
 - using MVFs obtained by combination of cyclic registration and artifact model is suitable for application in IGRT

Thank You!

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Parts of the reconstruction software were provided by RayConStruct[®] GmbH, Nürnberg, Germany.