Estimation of Bowtie Filter Attenuation from Reconstructed CT Images

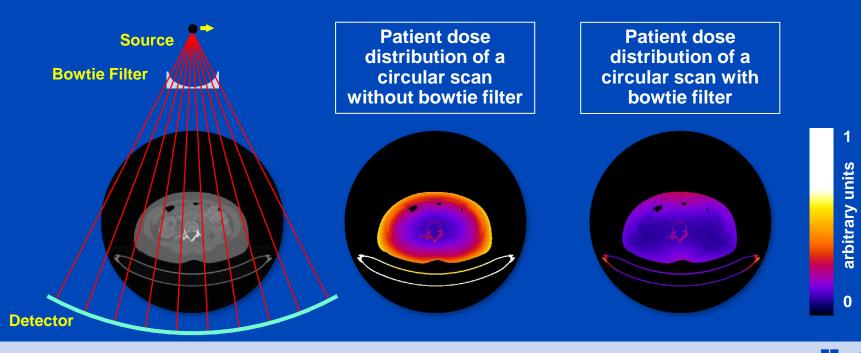
Joscha Maier, Stefan Sawall, and Marc Kachelrieß

German Cancer Research Center (DKFZ), Heidelberg, Germany



Motivation

- Commercial CT-scanners are usually equipped with a bowtie filter in order to optimize the patient dose distribution.
- Monte-Carlo dose calculations or statistical reconstruction algorithms require exact knowledge of the bowtie filter.
- The shape as well as the composition of the bowtie filter is usually not disclosed by the CT vendors.



Motivation

Prior Work

- Analysis of rawdata of a scan with empty gantry¹
 - → Rawdata not generally available
- Measurement of bow tie profiles using real-time dosimeter²
 - → Additional hardware required
- Measurement of bow tie profiles using radiochromic film³
 - → Additional hardware required

Proposed Approach

- In all cases the reconstructed CT images are available to the user
- Variance distribution of reconstructed CT images contain information on the bowtie filter shape.
- Analysis of the variance of reconstructed CT images of a calibrated object allows the estimation of the bowtie filter.

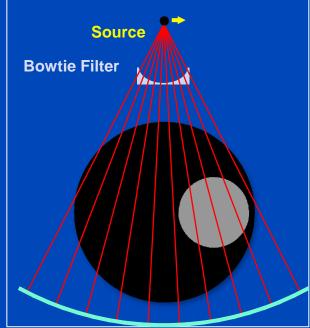
¹ B. R. Whiting et al., "Properties of preprocessed sinogram data in x-ray computed tomography," Med. Phys. 33(9), 3290 – 3303 (2006).
² B. R. Whiting et al., "Measurement of bow tie profiles in CT scanners using a real-time dosimeter," Med. Phys. 41(10), 101915-1 – 101915-7 (2014).
³ B. R. Whiting et al., "Measurement of bow tie profiles in CT scanners using radiochromic film," Med. Phys. 42(6), 2908 – 2914 (2015).



Workflow

Reconstruction of NCT Scans of an object with known intersection lengths and attenuation

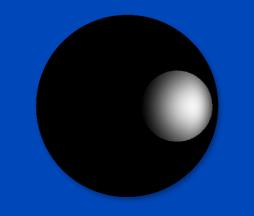
 $f_i = X^{-1} p_i$



Calculation of the variance of the reconstructed images (clipped to object)

$$\sigma_{f,meas}^2 = \frac{1}{N} \sum_{i=1}^{N} (f_i - \bar{f})^2.$$

$$e^{-\mu \cdot L_B} = \arg \min \left[\left(\sum (\sigma_{\rm f, \ sim}^2 - \sigma_{\rm f, \ meas}^2)^2 \right] \right]$$





Estimation of Bowtie Filter Attenuation: Variance

• Expectation value $n(E, \beta, \vartheta)$ of photons with energy *E* hitting an ideal detector element at position (β, ϑ) :

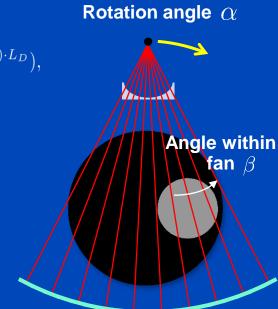
 $n(E,\beta,\vartheta) = n_0(E) \cdot e^{-\mu_B(E) \cdot L_B(\beta)} \cdot e^{-\mu_O(E) \cdot L_O(\vartheta,\beta)} \cdot e^{-\mu_P(E) \cdot L_P} \cdot (1 - e^{-\mu_D(E) \cdot L_D}),$

 μ_B = Attenuation coefficient of the bowtie

- μ_O = Attenuation coefficient of the object
- μ_P = Attenuation coefficient of the prefilter
- μ_P = Attenuation coefficient of the detector
- L_B = Intersection length through bowtie
- L_O = Intersection length through object
- L_P = Thickness of the prefilter
- L_D = Thickness of the detector

 $n_0 =$ Photon spectrum

• Since photon matter interaction follow Poisson statistics the variance $\sigma_n^2(E,\beta,\vartheta)$ of incident photon numbers equals its expectation value: $\sigma_n^2(E,\beta,\vartheta) = n(E,\beta,\vartheta)$





Estimation of Bowtie Filter Attenuation: Optimization

• Calculating the propagation of the variance of the incident photons, the variance of the projection values $\sigma_p^2(\beta, \vartheta)$ is given by:

$$\sigma_p^2(\beta, \vartheta) = \frac{\sum_E E^2 \sigma_n^2(E, \beta, \vartheta)}{\left[\sum_E E \sigma_n^2(E, \beta, \vartheta)\right]^2}$$

- The images $f\,$ are calculated from the projection data $\,p\,$ using a filtered backprojection:

 $f(x,y) = X^{-1}p(\beta,\vartheta)$

Since the filtered backprojection is a linear operation, the image variance is given by:

 $\sigma_{f,sim}^2(x,y) = (X^{-1} \circ X^{-1})\sigma_p^2(\beta,\vartheta)$

• Finally, the bowtie filter attenuation $e^{-\mu(E)L(\beta)}$ can be estimated by minimizing the squared difference between predicted and measured variance:

$$e^{-\mu(E) \cdot L_B(\beta)} = \underset{\mu(E), L(\beta)}{\operatorname{arg\,min}} \left[\sum_{x,y} \left(\sigma_{\mathrm{f,\,sim}}^2(x,y) - \sigma_{\mathrm{f,\,meas}}^2(x,y) \right)^2 \right]$$



Estimation of Bowtie Filter Attenuation: Implementation

- The x-ray spectrum is approximated using a semi-empirical model of Tucker et al.
- If the material of the bowtie is known, tabulated attenuation coefficients are used. Otherwise, the attenuation coefficient can be estimated using a linear combination of two basis materials:

 $\mu_B(E) = c_1 \cdot \mu_1(E) + c_2 \cdot \mu_2(E)$

• Estimation of the bowtie filter intersection lengths, which are assumed to be symmetric, at a given number of nodes $L[\beta_i]$. Determination of other intersection lengths by linear interpolation

 $L_B(\beta) = w_i \cdot L[\beta_i] + (1 - w_i) \cdot L[\beta_{i+1}]$

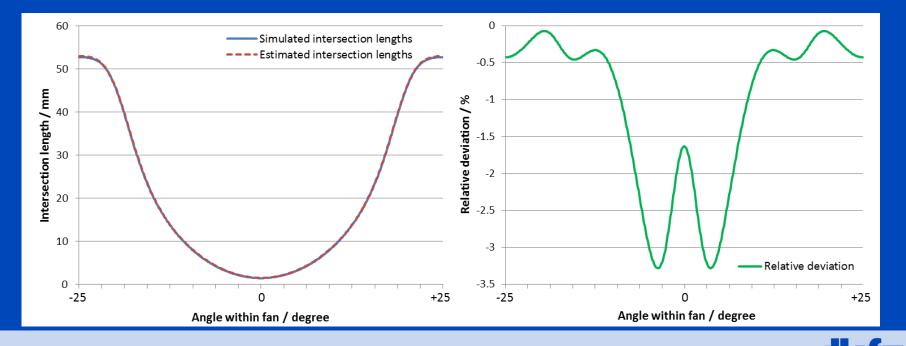
Estimated parameters:

 $c_1, c_2, L[n_i]$, intensity



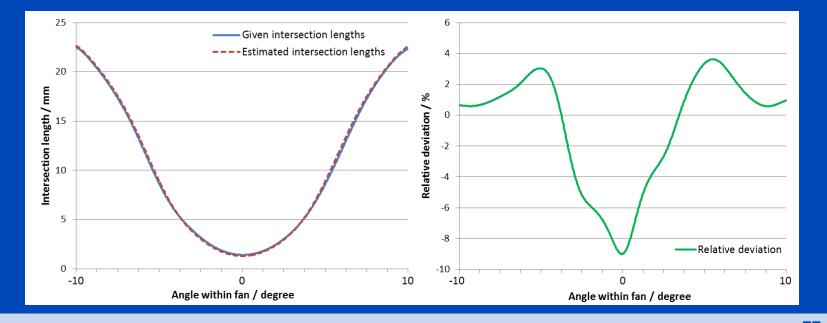
Results: Simulated Data

- A homogenous cylindrical PMMA phantom was used to simulate a 120 kV CT scan.
- A total number of 20 scans was simulated and 18 nodes were used for the estimation of bowtie filter intersection lengths.
- Simulated intersection lengths of a PTFE bowtie filter are compared to the estimated intersection lengths.



Results: Measured Data

- Measurements were conducted on a flat detector cone-beam CT with 20° fan angle at 120 kV, that is equipped with a known PTFE bowtie filter
- 20 Scans of a cylindrical PMMA phantom
- Given intersection lengths of the bowtie filter of the cone-beam system are compared to the estimated intersection lengths



Conclusion

- We proposed a novel approach to estimate bowtie filter attenuation from reconstructed CT images of calibrated objects.
- There is no need for special hardware except for a simple homogenous phantom.
- Simulations as well as measurements demonstrated that the proposed approach provides accurate attenuation curves with deviations less than 5 %.



Thank You!



Marc Kachelrieß, German Cancer Research Center (DKFZ), Heidelberg, Germany

Parts of the reconstruction software RayConStruct-IR were provided by RayConStruct[®] GmbH, Nürnberg, Germany.

