Computed Tomography 2.0

Photon-Counting and Artificial Intelligence

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PHOTON-COUNTING CT



Availability of Diagnostic Photon-Counting CT

	Sensor material	Detector pixel size at iso	Pixel binning	FOM	Bins	FDA	Pubs	Installations
Canon	CdZnTe	210 µm	3×3, 1×1	50 cm	5	no	1	1 prototype (Japan)
GE	Si, edge on	400 × 400 µm	?	?	?	no		1 experimental (Sweden), 2 prototypes (USA)
Philips	CdZnTe	274 × 274 µm	?	50 cm	5	no	≈22	1 experimental setup (France)
Samsung Omnitom Elite	CdTe	703 × 707 μm / 351 × 423 μm / 117 × 141 μm	5×6, 3×3, 1×1	30 cm	3	yes	1	?
Siemens CounT	GOS/CdTe dual source	700 × 600 μm / 250 × 250 μm	2×2, 1×1	50 / 28 cm	4	no	≈50	3 experimental systems (Germany, USA)
Siemens CountPlus	CdTe	150 × 176 µm	2×2, 1×1	50 cm	4	no	≈11	3 prototypes (Czech, Sweden, USA)
Siemens Alpha	CdTe/CdTe dual source	2 · 150 × 176 μm	2×2, 1×1	50 / 36 cm	4	yes	≈40	about 100 worldwide



Face on design (all others)



Image courtesy of Siemens Healthineers

The additional factor 2 in the detector pixel size column indicates that some scan modes may use binning.



Diagnostic CT (Conventional Detector) of a Low Contrast Phantom



Diagnostic routine head protocol. 34 mGy CTDI_{vol}.



Photon Counting Detector CT of a Low Contrast Phantom



Same dose. At same spatial resolution (MTF) better image quality.



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C = 0 HU, W = 80 HU



Requirements for CT: up to 10⁹ x-ray photon counts per second per mm². Hence, photon counting only achievable for direct converters.



≈ 1 kV

Energy-Selective Detectors: Improved Spectroscopy, Reduced Dose?

Ideally, bin spectra do not overlap, ...



Spectra as seen with 4 bins after having passed a 32 cm water layer.



Energy-Selective Detectors: Improved Spectroscopy, Reduced Dose?

... realistically, however, they do!



Spectra as seen with 4 bins after having passed a 32 cm water layer.



Photon Events

- Detection process in the sensor
- Photoelectric effect (e.g. 80 keV)





Photon Events

- Detection process in the sensor
- Compton scattering or K-fluorescence (e.g. 80 keV)





Photon Events

- Detection process in the sensor
- Photoelectric effect (e.g. 30 keV), charge sharing





No Electronic Noise!

- Photon counting detectors have no electronic noise.
- Extreme low dose situations will benefit
 - Pediadric scans at even lower dose
 - Obese patients with less noise

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- Industrial CT with very long exposure times per frame



Readout noise only. Single events hidden!

PC (Dectris)

No readout noise. Single events visible!

18 frames, 5 min integration time per frame, x-ray off



Siemens Naeotom Alpha The World's First Photon-Counting CT

• Tubes

- tube A: 120 kW
 tube B: 120 kW
 ≈ ¼ MW
- Focal spot size down to 181 μm

Detectors \bullet

- pixel size down to 150 μm
- 288 detector rows
- 2752 detector columns
- Speed
 - up to 4 rotations per second
 - up to 737 mm/s scan speed
- 50 cm FOM





Detector Pixel Force vs. Alpha



ASG information taken from [J. Ferda et al. Computed tomography with a full FOV photon-counting detector in a clinical setting, the first experience. European Journal of Radiology 137:109614, 2021]





Kachelrieß, Kalender. Med. Phys. 32(5):1321-1334, May 2005





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Photon Counting used to Maximize CNR

- With PC, energy bin sinograms can be weighted individually, i.e. by a weighted summation.
- To optimize the CNR the optimal bin weighting factor w_b is given by (weighting after log):

$$w_b \propto rac{C_b}{V_b}$$

The resulting CNR is

$$\operatorname{CNR}^2 = \frac{\left(\sum_b w_b C_b\right)^2}{\sum_b w_b^2 V_b}$$

At the optimum this evaluates to

$$CNR^2 = \sum_{b=1}^{B} CNR_b^2$$





The two ROIs are used to measure the CNR





Material Decomposition or CNR Maximization?

- W =soft tissue (water) signal, X =iodine signal •
- Assume same noise N, e.g. 50 HU, in both bin measurements M_1 and M_2 •
 - Var M_1 = Var M_2 = N^2 regardless of whether iodine is present or not
- PCCT measurement
 - Measurement 1 (high bin): $M_1 = W + 0.25 X$
 - Measurement 2 (low bin): $M_2 = W + 0.5 X$
- Material decomposition •
 - Estimated iodine: $4(M_2 - M_1)$ Variance = 16 (Var M_2 + Var M_1) = 32 N^2
 - Estimated soft tissue: $2 M_1 - M_2$
- CNR maximization
 - Compute (1 w) M_1 + w M_2
 - lodine value minus soft tissue value
 - Maximizing CNR yields w = 2/3

 $SNR^2 = X^2 / 32 N^2$ Variance = 4 Var M_1 + Var M_2 = 5 N^2 $SNR^2 = W^2 / 5 N^2$

Variance = $(1 - w)^2 N^2 + w^2 N^2 = (1 - 2 w + 2 w^2) N^2$

Contrast = (1 - w) 0.25 X + w 0.5 X=

 $CNR^2 = 5 X^2 / 16 N^2$

 $CNR^2 = X^2 / 16 N^2$

 $CNR^2 = X^2 / 4 N^2$



Linear Mixing Techniques



C = 300 HU, W = 1400 HU



Summary on PCCT

Higher efficiency

- better image quality
- reduced measurement times

No electronic noise

- very long exposures possible
- potential to overcome photon starvation

Spectral information on demand

- material discrimination
- artifact reduction
- combination with DECT acquisition possible and reasonable
- High frame rates also for off-the-shelve PC detectors
 - can be of interest for inspection tasks



ARTIFICIAL INTELLIGENCE









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Sparse View Restoration Example



Yo Seob Han, Jaejun Yoo and Jong Chul Ye. Deep Residual Learning for Compressed Sensing CT Reconstruction via Persistent Homology Analysis. ArXiv 2016.

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Component-Specific Denoising/Desparsifying

- We assume to have one long-acquisition scan of the component
- Generate training data via random transformations and deformations
- Generate datasets for training, validation and :
 - GT: Long-acquisition ground truth
 - UN: undersampled + noise reconstruction (80 projections, Poisson noise)
 - N: Noisy reconstruction (800 projections, with Poisson noise)
- Train three U-Nets
 - Sh-Unet-MSE: Shallow structure (3× downsampling, initial filter size: 16) with MSE
 - Unet-MSE: Deeper structure (4× downsampling, initial filter size: 16) with MSE
 - Unet-Adv: Deeper structure trained in WGAN-GP setting with perceptual and MSE component
- All networks are trained on patches of size 256² on the UN dataset





Results Test Data (UN) · Sh-Unet-MSE





Ground Truth







Shallow Unet















Deep Adversarial Unet







Standard reconstruction



Simulation-based removal of

- beam hardening artifacts
- off-focal radiation artifacts
- focal spot blurring artifacts Presented at 1 2016
- detector blurring artifacts
- scatter artifacts
- ...

Simulation-based artifact correction



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J. Maier, M. Kachelrieß et al. Simulation-based artifact correction (SBAC) for metrological computed tomography. Meas. Sci. Technol. 28(6):065011, May 2017.

Deep Scatter Estimation (DSE)



Monte Carlo Scatter Estimation

- Simulation of photon trajectories according to physical interaction probabilities.
- 1 to 10 hours per tomographic data set approximates Simulating a large number of photon the actual scatter distribution

Suplete scatter distribution



Deep Scatter Estimation

Network architecture & scatter estimation framework





Simulation Study: Training Data

- Simulation of 16416 projections using different objects and parameter settings to train the DSE network.
- Training on a GeForce GTX 1080 for 80 epochs using the Keras framework, an Adam optimizer and a mini-batch size of 16.





Simulation Study: Testing Data

 Simulation of a tomography (720 projection / 360°) of five components using acquisition parameters that differ from the ones used to generate the training data set.







Scatter estimates for simulated testing data

Model	Primary intensity	Scatter ground truth (GT)	Kernel - GT / GT	Hybrid - GT / GT	DSE - GT / GT
60 mm		9	13%	7%	1%
erection of the second se			mean absolute percentage error over 3600	mean absolute percentage error over 3600	mean absolute percentage error over 3600
A main and a main	8		projections	projections	projections
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Street	C = 0.5, W = 1.0	C = 0.015, W = 0.020	C = 0%, W = 50%	C = 0%, W = 50%	C = 0%, W = 50%





CT reconstructions of scatter corrected testing data



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Application to Measured Data

- Measurement at DKFZ table-top CT
- Tomography of aluminum profile
- 720 projections, 360°
- 110 kV Hamamatsu micro-focus tube
- Varian flat detector



	Training	Testing		
Components				
Detector elements	768×768	768×768		
Source-detector distance	580 mm	580 mm		
Source-isocenter distance	100 mm, 110 mm, 120 mm	110 mm		
Tilt angle	0°, 30°, 60°, 90°	0°		
Tube voltage	100 kV, 110 kV, 120 kV	110 kV		
Copper prefilter	1.0 mm, 2.0 mm	2.0 mm		
Scaling	1.0	-		
Number of projections	8208	720		

Results Performance of DSE for measured data

Projection data



Reconstructions





A simple detruncation was applied to the rawdata before reconstruction. Images were clipped to the FOM before display. C = -200 HU, W = 1000 HU.



To learn why MC fails at truncated data and what significant efforts are necessary to cope with that situation see [Kachelrieß et al. Effect of detruncation on the accuracy of MC-based scatter estimation in truncated CBCT. Med. Phys. 45(8):3574-3590, August 2018].

J. Maier, M. Kachelrieß et al. Deep scatter estimation (DSE). SPIE 2017 and Journal of Nondestructive Evaluation 37:57, July 2018. J. Maier, M. Kachelrieß et al. Robustness of DSE. Med. Phys. 46(1):238-249, January 2019.



DSE

DSE for Cross-Scatter Correction (xDSE)



Images C = 40 HU, W = 300 HU, difference images C = 0 HU, W = 300 HU

J. Erath, T. Vöth, J. Maier, E. Fournié, M. Petersilka, K. Stierstorfer, and M. Kachelrieß. Deep learning-based forward and cross-scatter correction in dual source CT. Med. Phys. 48:4824–4842, July 2021.



DSE for Coarse ASG



J. Erath, M. Kachelrieß et al. CT-Meeting 2022. This paper received the "Highest Impact Paper Award" for the highest impact score at the 7th International Conference on Image Formation in X-Ray Computed Tomography in June 2022



Conclusions on DSE

- DSE needs about 1 ms per projection.
- DSE is a fast and accurate alternative to MC simulations.
- DSE outperforms other approaches in terms of accuracy and speed.
- Facts:
 - DSE can estimate scatter from a single (!) x-ray image.
 - DSE generalizes well to different geometries, scanners and objects.
 - DSE variants for cross-scatter and coarse ASG scatter prediction are available.
 - DSE may outperform MC even though DSE is trained with MC.
- DSE is not restricted to reproducing MC scatter estimates.
- DSE can rather be trained with any other scatter estimate, including those based on measurements.
- DSE can also be used to simulate scatter (at somewhat lower accuracy).



uDSE – Basis Principle

















Summary on AI for CT Image Formation

- Powerful tool that allows to solve yet unsolved problems
 - Underdetermined situations, where AI brings in prior knowledge
 - Computational demanding problems, where AI reduces the compute time
- Results have to be taken with care
 - Images often look great, but are they true?
 - Utilizing too much prior knowledge will result in fake content
 - Proves do not exist, the networks' output cannot be eplained
- Vendors may tend to overemphasize the benefits from AI
 - Sale by nice looking images



Thank You!

- This presentation will soon be available at www.dkfz.de/ct.
- Job opportunities through DKFZ's international PhD or Postdoctoral Fellowship programs (marc.kachelriess@dkfz.de).
- Parts of the reconstruction software were provided by RayConStruct[®] GmbH, Nürnberg, Germany.



The 8th International Conference on Image Formation in X-Ray Computed Tomography

August 5 – August 9, 2024, Bamberg, Germany www.ct-meeting.org



Conference Chair Marc Kachelrieß, German Cancer Research Center (DKFZ), Heidelberg, Germany

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