Towards 4D Interventional Guidance: Reconstructing Interventional Tools From Four X-Ray Projections using a Deep Neural Network

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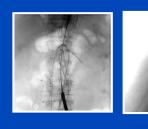


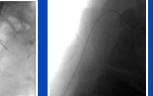


Motivation

Today's Interventional guidance (IG)

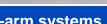


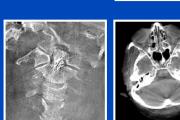




Fluoroscopy (2D + time)

limited information about 3D structure of interventional tools (e.g. of stents)





Tomography (3D) no temporal information

C-arm systems

Tomographic (4D) interventional guidance

- could provide full spatiotemporal information about interventional tools •
- could enable new minimally invasive radiological interventions 0

Currently, tomographic interventional guidance would result in excessively high dose due to the need for continuous CBCT scanning.



Prior Work

Prior work¹ showed feasibility of reconstructing interventional tools from 16 projections if patient prior is available. Has been further improved to account for patient motion via registration of the prior scan².

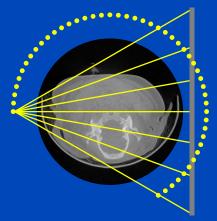
Drawbacks of resulting pipeline

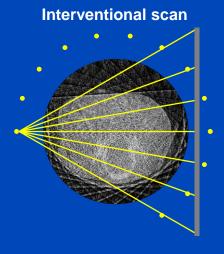
- Dose ~16 times higher than for standard fluoroscopic IG
- Registration² of prior scan is too computing-intensive to realize the pipeline in real-time
- clinically impractical

Develop a novel deep learning-based pipeline

- Deep Tool Extraction (DTE) Extract the interventional tools in the projection domain
- Deep Tool Reconstruction (DTR) Segment interventional tools in reconstructions in sparsely reconstructed volumes

Prior scan



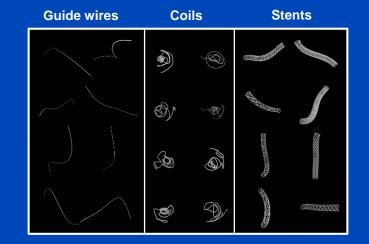


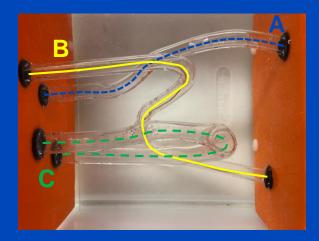


Simulations & Measurements

Simulations

- Generated 3D models of guide wires, stents and coils of random deformations, diameters and shape matching those parameters of commercially available tools
- Simulated in a C-arm Cone-Beam CT (CBCT) geometry to generate projection data and reconstructions





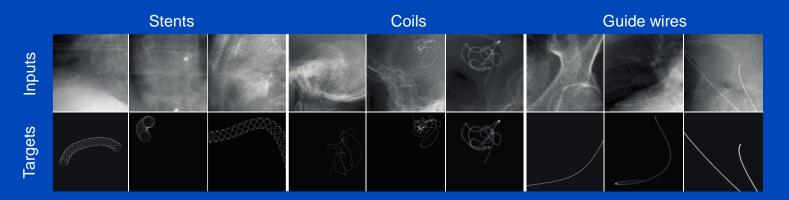
Measurements

- We scanned commercially available stents, guide wires and coils to test our method using both a custom intervention phantom and a commercial brain vessel phantom
- The projections of these scans were superimposed on projections of CBCT patient scans



Deep Tool Extraction

- The CNN (U-net) is trained to extract interventional tools from projections
- During training we add forward projections of 3D models on randomly cropped patches of patient scans
- Tools-only projections serve as ground truth
- To reduce amount of training data where interventional tools are outside patient reject Ps with mean(P) ≤ 1 .
- Data augmentation include
 - Random flipping of the tools horizontally
 - Additive Poisson noise
 - Multivariate Gaussian blurring
- During training we minimize the L₁-loss using the Adam optimizer



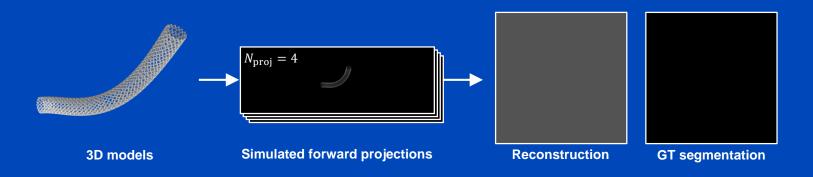


Deep Tool Reconstruction

- The CNN (U-net) segments interventional tools, that were sparsely FDK reconstructed from four x-ray projections
- It uses 13 consecutive slices (corresponding to 1.3 mm) as input to leverage 3D information
- Voxel representations of centered slices serve as ground truth
- During training we minimize the soft Dice loss with Laplace smoothing between network output y and ground truth \hat{y}

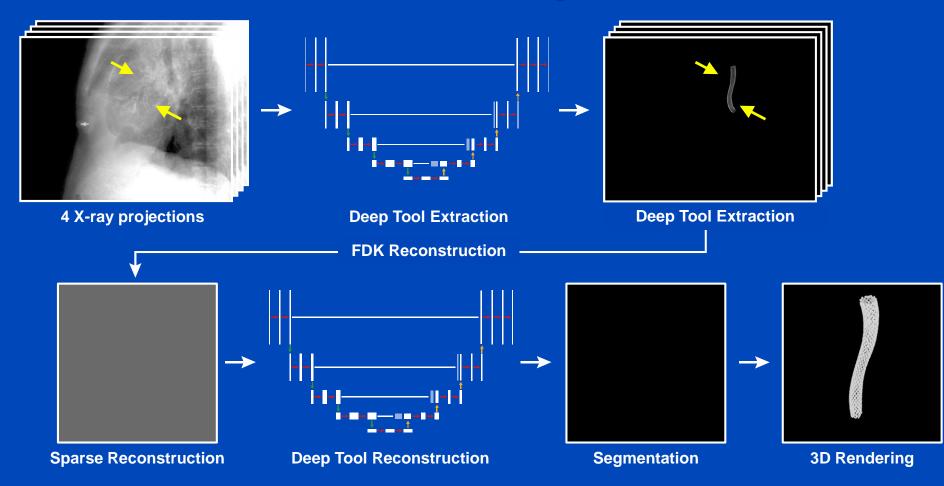
$$L_{\rm SD}(y, \hat{y}) = 1 - \frac{2\sum_{k} y_{k} \hat{y}_{k} + 1}{\sum_{k} y_{k} + \sum_{k} \hat{y}_{k} + 1}$$

using the Adam optimizer.





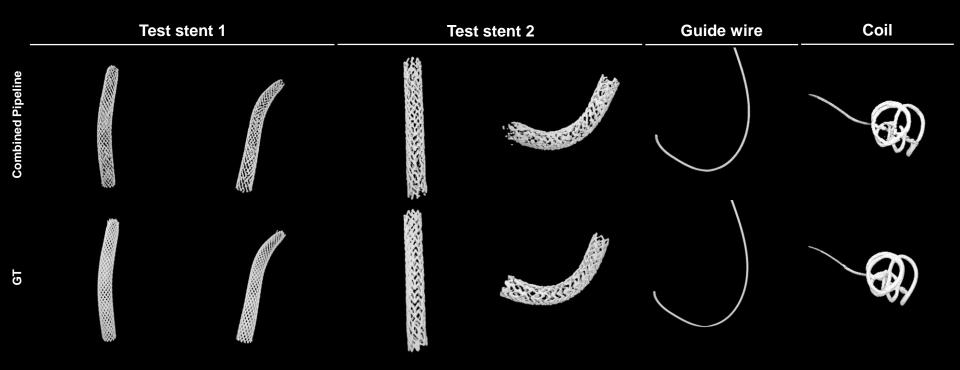
Combined Pipeline







Results Combined Pipeline





Conclusion & Outlook

Deep Tool Extraction

- eliminates the need for a prior scan and registration step
 - ► This eases clinical workflow
 - ► No problems with patient motion
 - ► Complete pipeline is applicable in real time

Deep Tool Reconstruction

- can reconstruct interventional tools from only 4 x-ray projections with high accuracy
- currently limited to the case were the tool doesn't move between the four projections

Future work comprises

- investigating the performance for a combination of tools (e.g. stents around guide wire)
- testing the pipeline on clinical data



Thank You!

The 6th International Conference on Image Formation in X-Ray Computed Tomography

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Conference Chair: Marc Kachelrieß, German Cancer Research Center (DKFZ), Heidelberg, Germany

This presentation will soon be available at www.dkfz.de/ct. We are hiring for this and similar topics! Contact: marc.kachelriess@dkfz.de. Parts of the reconstruction software were provided by RayConStruct[®] GmbH, Nürnberg, Germany.