Iterative Motion-Compensated Reconstruction for Image-Guided Radiation Therapy

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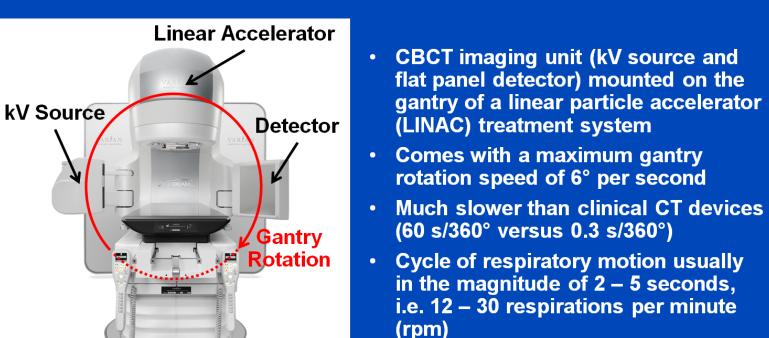
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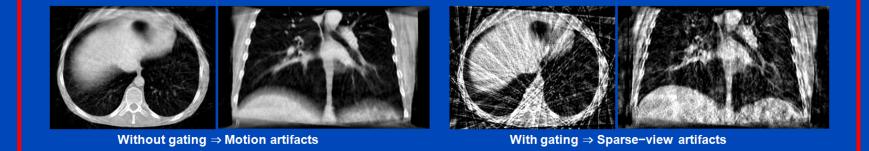
Purpose:

In Image–Guided Radiation Therapy (IGRT) an additional kV imaging system orthogonal to the linear particle accelerator provides information for an accurate patient positioning. However, due to the limited gantry rotation speed during treatment the typical acquisition time is much longer than the patient's breathing cycle resulting in low image quality. In particular, respiratory motion causes severe artifacts such as blurring and streaks in tomographic images. Compensating for motion is an interesting option and capable of providing high quality respiratorycorrelated 4D volumes. Our purpose is to estimate the motion and compensate for it in case of 4D cone-beam CT (4DCBCT) scans and in particular 4D on-board CBCT scans for IGRT [1]. The particular challenge is to do this without knowledge from prior scans and without specific requirements on the acquisition as done in references [2,3].





Phase Gating – Angular Spacing Retrospective phase gating reduces motion artifacts.



BUT: Gating results in an enlarged angular spacing of projection bins.

like the cyclic motion patterns of respiration. A potential overcorrection by the temporal part is avoided by iterative refinement.

Results:

The test set consists of synthesized data, obtained by deforming a

The motivation for the presented work is to provide high quality respiratory-correlated 4D volumes from on-board CBCT scans without any particular slow, multiple or adaptive gantry rotation technique and without knowledge from prior scans like planning CTs.

Estimation of Motion Vector Fields (MVF)

• Apply CEVFS to minimize E

CEVF by CEVF

Nomenclature: $\prod_{l=1}^{j} T_{l}^{l+1} := T_{1}^{2} \circ T_{2}^{3} \circ \ldots \circ T_{j}^{j+1}$ $T_{N+j}^{N+j+1} :\Leftrightarrow T_{j}^{j}$

Correction / Iteration

Apply error information equally on

With refinement after each CEVF

 $j \neq k$: $\mathbf{T}_{j}^{j+1} \leftarrow \mathbf{T}_{j}^{j+1} - \frac{E_{k} \circ \prod_{l=k}^{j-1} \mathbf{T}_{l}^{l+1}}{E_{k} \circ \prod_{l=k}^{j-1} \mathbf{T}_{l}^{l+1}}$

 $j = k: \quad \mathbf{T}_{j}^{j+1} \leftarrow \mathbf{T}_{j}^{j+1} - \frac{E_{k}}{N}$

Constant gantry rotation speed

Almost regular breathing pattern

Almost constant angular spacing

Displacement curve of a fictitious pixel

respiratory cycle

w/o temporal constrai

with temporal constraint

for all 20 phase

over complete

MVFs for adjacent phases first

 $I_{n-1} \longrightarrow I_n \longrightarrow I_{n+1} \frown$

 $I_2 \checkmark^{T_1^*} I_1 \checkmark^{T_N^*} I_N \checkmark$

MVFs for non-adjacent phase pairs

 $\mathbf{T}_{i}^{k} \leftarrow \mathbf{T}_{i}^{j+1} \circ \mathbf{T}_{i+1}^{k}$

Cyclic breathing motion patterns

Concatenation error vector fields

Incorporate temporal constraints

Minimization of cost function

 $E := \sum_{k} \left\| \mathbf{E}_{k} \right\|^{2} = \sum_{k} \left\| \left(\prod_{j=1}^{k} \mathbf{T}_{j}^{j+1} \right) \right\|_{j}^{2} = \sum_{k=1}^{k} \left\| \left(\prod_{j=1}^{k} \mathbf{T}_{j}^{j+1} \right) \right\|_{j}^{2} = \sum_{k=1}^{k} \left\| \mathbf{E}_{k} \right\|^{2} = \sum_{k=1}^{k} \left\|$

given by concatenation

(CEVF) E_k

<u>Initialization</u>

20

e.g. 20 phases)

approaches of adjace hases first, tempora

constraints, and

terative correction

Motion Estimation 2:

MVFs are estimated

using the adjacent phases first approach, but without any temporal constraint

and iterative correct

Our Motion Estimation

is used with adjacent

Motion Compensation (MoCo)

Ground truth in end-exhale

Backprojection on (straight)

acquisition lines of a projection

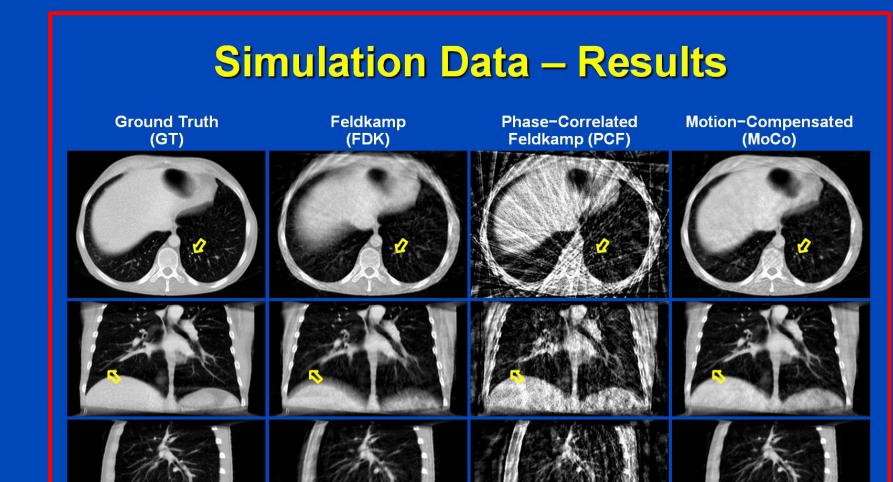
acquired in end-inhale

Warped backprojection



- Use of all projections
- Even those of other phase bins Compensate for motion using motion vector fields (MVF) determined via motion estimation
- In our case motion estimation is performed on phase-correlated Feldkamp images
- Backproject along straight lines, then warp with respect to the MVFs (corresponds to backprojection along curved lines)

- Projection data p, phase-correlated reconstruction operator X_{PCF}^{-1} , MVF T_j^i from phase bin j to phase bin i $f_{\mathrm{MoCo}(i)} := \sum \left(\mathsf{X}_{\mathrm{PCF}(j)}^{-1} p \right) \circ \mathrm{T}_{j}^{i}$



clinical patient dataset, and patient scans including RPM information the On–Board acquired with Imager's[®] and the TrueBeam'sTM integrated kV imaging unit (Varian Medical Systems, Palo Alto, USA).

The standard Feldkamp CBCT reconstruction results in a poor temporal resolution. The respiratorycorrelated 4DCBCT reconstruction comes with a high temporal resolution and reduced motion blurring, but image quality is deteriorated due to the increased angular spacing of applied projections. Our motion compensation with cyclic motion estimation shows a good temporal resolution and highly reduced impact of few-view artifacts at the same time. The registration algorithm shows low sensitivity on image artifacts and is able to recover respiratory motion. Finer details like pulmonary vessels hidden by motion or streak artifacts become visible in motion-compensated images. The drawback of potential underestimation of motion in case of initial motion compensation is reduced by a correction step.

Materials and Methods:

Standard CBCT reconstruction approaches, e.g. using Feldkamp algorithm [4], backproject all projection data without considering patient motion properly and thereby suffer from motion artifacts. Retrospective phase gating in case of 4DCBCT sorts the data into different sets according to the respiratory motion phase. Performing a separate reconstruction of each phase reduces motion artifacts, but results in artifacts due to an increased angular spacing. Thus, sparse-view artifacts and a high noise level deteriorate the image quality.

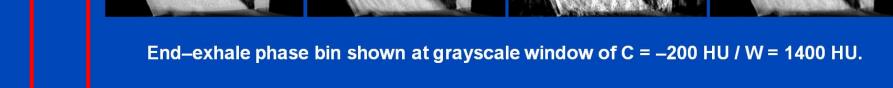
State-of-the-art methods for estimation of the motion vector fields suffer from the low sampling of the data and thus from image artifacts that appear in the reconstructions. In applications like ours conventional registration algorithms tend to register artifacts rather than anatomy. Our idea is to address this problem by a new deformable registration algorithm mainly based on a cyclic regularization that avoids the algorithm being sensitive to the above-mentioned streak artifacts. Our new deformable registrations algorithm consists of a spatial registration method [5] and a temporal correction part given by constraints



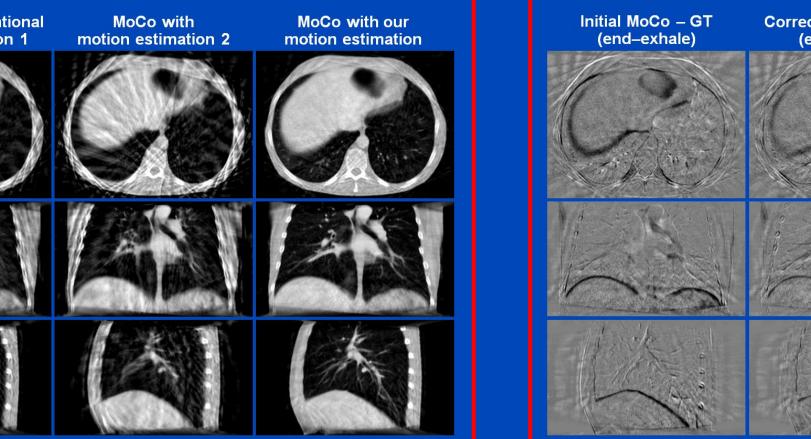
Simulation Data – Results

Iterative Motion Compensation

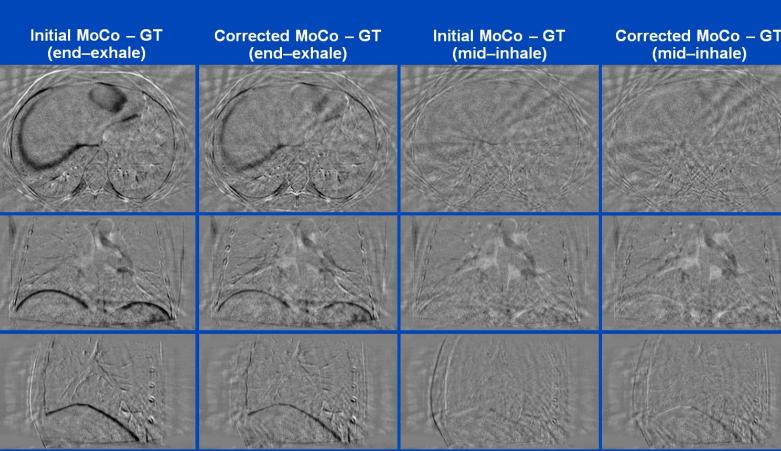
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Simulation Data – Results

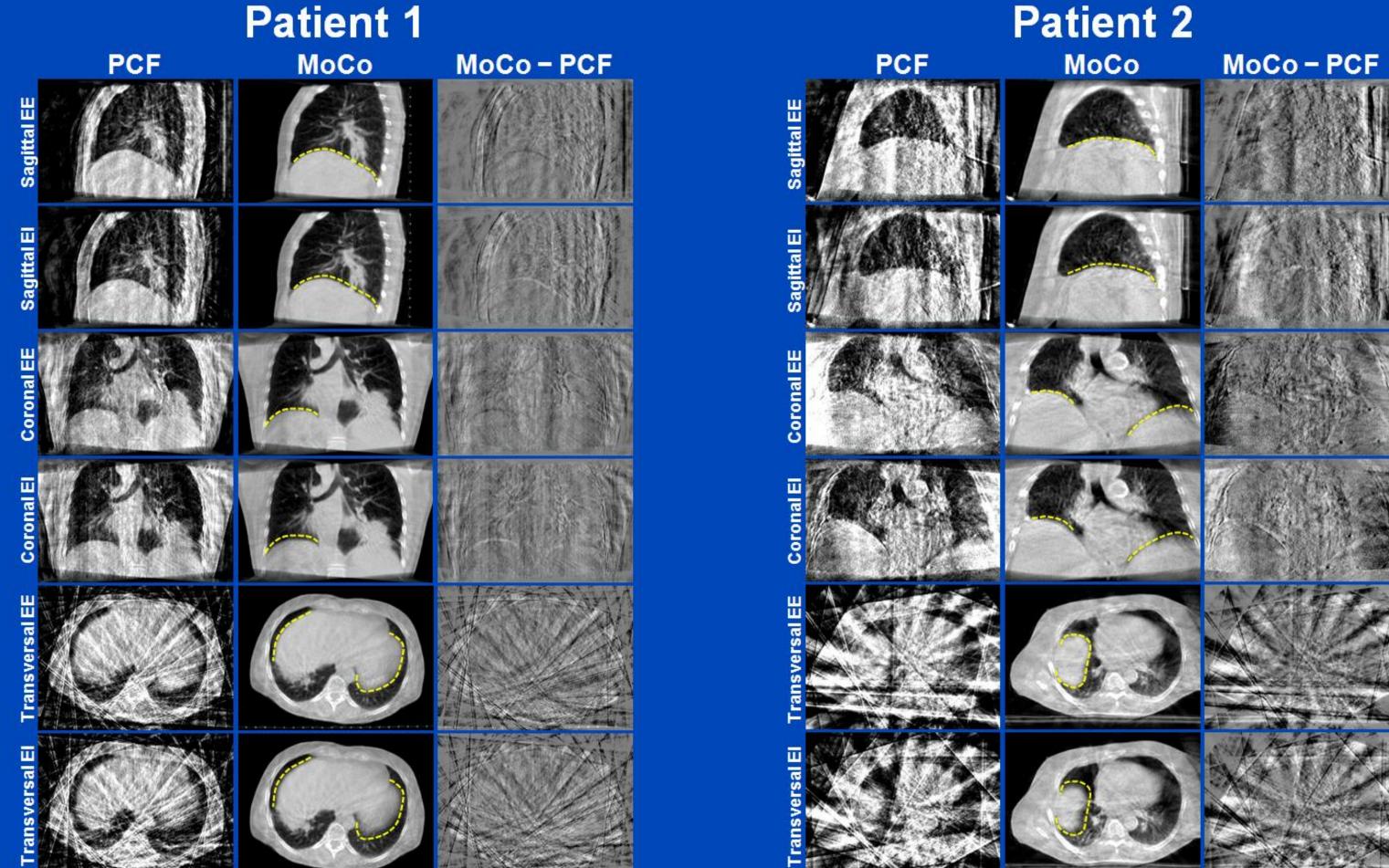


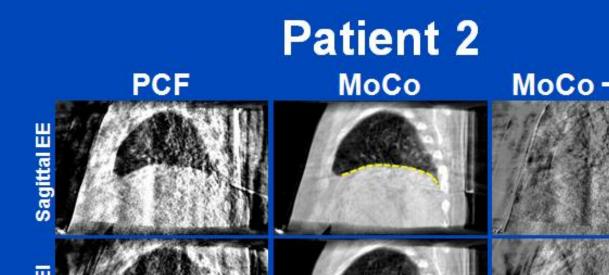
End–exhale phase bin shown at grayscale window of C = -200 HU / W = 1400 HU



C/W = 0 HU / 1000 HU.

Patient Data – Results





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References:

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For two different patients the end-exhale (EE) and end-inhale (EI) phase bin are shown at grayscale window of C = -200 HU / W = 1400 HU. Difference images are shown at C = 0 HU / W = 2000 HU and the dotted lines mark edge positions in end-exhale.

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